

Description of parameter file for “channelflow” code (including rotation in the y-direction, scalar equation for stratification)

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1. Filename is “condition.param”

2. [Example]

```
1.      nu = 0.25
2.      dtmax = 0.1
3.      CFLmin = 0.1
4.      CFLmax = 0.9
5.      nRac = 20.0
6.      T0 = 0.0
7.      T1 = 10.0
8.      dT = 1.0
9.      Omega = 0.0
10.     Usurface = 0.0
11.     isurfp = 0
12.     Up0 = 0.0
13.     Up = 0.0
14.     Op0 = 0.0
15.     Op = 0.0
16.     kpx = 0.0
17.     kpz = 0.0
18.     ishearstress = 0
19.     tau12 = 0.0
20.     tau32 = 0.0
21.     ihyper = 0
22.     nuu = 0.0
23.     iscalar = 0
24.     g = 0.0
25.     kappa = 1.0
26.     BC = DbDt
27.     bottomvalue = 0.0
28.     topvalue = 1.0
29.     sbound = 0
30.     smax = 1.0
31.     smin = 0.0
32.     dPdx = 0.0
33.     iforce = 0
34.     kfmin = 3.5
35.     kf = 4.0
36.     kfmax = 4.5
37.     ef = 0.4
38.     forcingtime = 0.0
39.     iLES = 0
40.     baseflow = PlaneCouette
41.     timestepping = CNRK2
42.     initstepping = SMRK2
43.     nonlinearity = Rotational
44.     dealiasing = DealiasXYZ
45.     taucorrection = true
46.     constraint = PressureGradient
47.     Ubulk = 0.0
48.     Lx = 2.0
49.     Ly = 2.0
50.     Lz = 2.0
```

3. There are 50 parameters totally; many of them can be not included in a “condition.param” file if using the default values. The order is arbitrary, but the format “name = value” must be followed for each parameter.

4. [Explanation] (R: double precision real number; I: integer number)

nu = 0.25: R; kinetic viscosity; the default value is 0.25

dtmax = 0.1: R; maximum time step for time marching; the default value is 0.1

CFLmin = 0.1 : R; minimum CFL number; the default value is 0.1

CFLmax = 0.9 : R; maximum CFL number; the default value is 0.9

nRac = 20.0: R; maximum local Rayleigh number refer to $Ra_c=657.511$; the default value is 20.0

T0 = 0.0 : R; initial time; the default value is 0.0

T1 = 10.0 : R; final time; the default value is 10.0

dT = 1.0 : R; time step to output assessments (such as spectrum); the default value is 1.0

Omega = 0.0 : R; rotation rate in the y-direction; the default value is 0.0

U_{surface} = 0.0 : R; mean velocity on top surface; the default value is 0.0;

isurf_p = 0 : I; identification of adding perturbation on top; the default value is 0; isurf_p=0: no perturbation;

isurf_p=1: $u=U_{surface}+Up_0*\sin(Op_0*t)+Up*\sin(Op*t-kpx*x*2\pi/Lx-kpz*z*2\pi/Lz)$; $v=w=0$

isurf_p=2: $u=U_{surface}$; $v=Up_0*\sin(Op_0*t)+Up*\sin(Op*t-kpx*x*2\pi/Lx-kpz*z*2\pi/Lz)$; $w=0$

isurf_p=3: $u=U_{surface}$; $v=0$; $w=Up_0*\sin(Op_0*t)+Up*\sin(Op*t-kpx*x*2\pi/Lx-kpz*z*2\pi/Lz)$

Up₀ = 0.0 : R; perturbation velocity (zero mode); the default value is 0.0;

Up = 0.0 : R; perturbation velocity; the default value is 0.0;

Op₀ = 0.0 : R; frequency for zero mode; the default value is 0.0;

Op = 0.0 : R; frequency; the default value is 0.0;

kpx = 0.0: R; the default value is 0.0

kpz = 0.0: R; the default value is 0.0

ishearstress = 0: I; identification of using shear stress boundary condition; if ishearstress = 0, Dirichlet BC; if ishearstress = 1, shear stress BC, isurf_p=1 or 3 cannot be used if using shear BC; the default value is 0

tau12 = 0.0: R; $\tau_{12}=(\partial u/\partial y+\partial v/\partial x)$; the default value is 0.0

tau32 = 0.0: R; $\tau_{32}=(\partial w/\partial y+\partial v/\partial z)$; the default value is 0.0

i_{hyper} = 0: I; identification of using hyper-viscosity; if i_{hyper}=0, no hyper-viscosity is included, if i_{hyper}=1, hyper-viscosity will be included in momentum equations; the default value is 0

nuu = 0.0: R; magnitude of hyper-viscosity; the default value is 0.0

iscalar = 0 : I; identification of including scalar equation; the default value is 0; if iscalar=0, then scalar equation is not included; if iscalar=1, then scalar equation is included, but scalar does not effect momentum equation; if iscalar=2, then scalar equation is included, and scalar effect momentum equation (stratification). Note, set iscalar=0 if you don't want to compute a scalar equation, and it will save more than 25% CPU cost.

g = 0.0 : R; value of gravitational acceleration, which describes the density fluctuation effect in momentum equation; the default value is 0.0;

kappa = 1.0 : R; diffusion coefficient for scalar equation; the default value is 1.0

BC = DbDt : ={DbDt, DbNt, NbDt, NbNt}; boundary condition for scalar equation; the default value is DbDt; upper “D”, “N” mean Dirichlet and Neumann, lower “b”, “t” mean bottom and top

bottomvalue = 0.0: R; value of scalar boundary condition at bottom; the default value is 0.0

topvalue = 1.0: R; value of scalar boundary condition at top; the default value is 1.0

sbound = 0: I; set scalar bound or not; if sbound=1 or 3, $s \leq s_{max}$; if sbound=2 or 3, $s \geq s_{min}$; if sbound=-1 or -3, check $s \leq s_{max}$ but not set; if sbound=-2 or -3, check $s \geq s_{min}$ but not set; otherwise, no bound; the default value is 0 (no bound)

smax = 0.0: R; maximum value of scalar; the default value is 1.0

smin = 0.0: R; minimum value of scalar; the default value is 0.0

dPdx = 0.0: R; mean pressure gradient; the default value is 0.0

iforce = 0: I; identification of including Gaussian forcing; the default value is 0; if iforce=0, then Gaussian forcing is off; if iforce=1, then Gaussian forcing is on; Gaussian forcing range is $k_{\min} < k < k_{\max}$, the peak wave-number is k_f , the energy input rate is ϵ_f , and until forcingtime

- $k_{\min} = 3.5$: R; the default value is 3.5
- $k_f = 4.0$: R; the default value is 4.0
- $k_{\max} = 4.5$: R; the default value is 4.5
- $\epsilon_f = 0.4$: R; the default value is 0.4
- forcingtime = 0.0: R; the default value is 0.0 (won't stop forcing if forcingtime ≤ 0.0)

iLES = 0: I; identification of LES (SGS) model; the default value is 0; if iLES=0, then no LES modeling; if iLES=others, different SGS models will be included according to this id number.

(We suggest using the default values for the following parameters)

baseflow = PlaneCouette: = {Zero, PlaneCouette, Parabolic}; base flow; the default value is PlaneCouette

timestepping = CNRK2: = {CNFE1, CNAB2, CNRK2, SMRK2, SBDF1, SBDF2, SBDF3, SBDF4}; time stepping scheme; the default value is CNRK2; currently, rotation and stratification is included only using CNRK2

initstepping = SMRK2: = {CNFE1, CNAB2, CNRK2, SMRK2, SBDF1, SBDF2, SBDF3, SBDF4}; initial time stepping scheme; the default value is SMRK2; not very serious, can be arbitrary or just use the default value

nonlinearity = Rotational: = {Rotational, Convection, Divergence, SkewSymmetric, Alternating, Alternating_, LinearAboutField, LinearAboutProfile}; method to include nonlinear term; the default value is Rotational; Rotational form is more accurate than Convection form and Divergence form for many cases, and Rotational form is much faster than SkewSymmetric form

dealiasing = DealiasXYZ: = {NoDealiasing, DealiasXZ, DealiasY, DealiasXYZ, DealiasX}; de-aliasing flag; the default value is DealiasXYZ

taucorrection = true: = {true, false}; tau correction or not; the default value is true;

constraint = PressureGradient : = {PressureGradient, BulkVelocity}; flow constraint to be enforced; the default value is PressureGradient

Ubulk = 0.0 : R; bulk velocity value; the default value is 0.0

Lx = 2.0 : R; box dimension in the x-direction; the default value is 2.0

Ly = 2.0 : R; box dimension in the y-direction; the default value is 2.0

Lz = 2.0 : R; box dimension in the z-direction; the default value is 2.0

5. Flags to run this program: there are one optional flag to run the program, and both flags are integer numbers. For example, “run 2”. Let's use a general form “run i” to explain the details.

I	Plot3D (ParaView)	TecPlot X (X>9)	U ⁺ in wall coordinates
±1	Yes	No	No
±2	No	Yes	No
±3	Yes	Yes	No
±4	Yes	No	Yes
±5	No	Yes	Yes
±6	Yes	Yes	Yes
±7	No	No	Yes
Otherwise (or not set)	No	No	No

If $i < 0$, then program won't save velocity/pressure/scalar data. For example, set $i = -8$ (or no input of i) in order to turn off everything.